

Variational factorization machines for preference elicitation in large-scale recommender systems

Jill-Jênn Vie¹ Tomas Rigaux¹ Hisashi Kashima²

¹ Inria Saclay, SODA team

² Kyoto University



京都大学
KYOTO UNIVERSITY

Preference elicitation

- Getting new info from new users is hard
- We need **side information** and to **model uncertainty**

Factorization Machines (FMs)

- FMs are a generalization of latent factor models (Rendle, 2012)
- Used for both regression and classification
- Sometimes better than their deep counterparts

In this paper

- Variational Factorization Machines
- Variational: Bayesian inference \rightarrow optimization

Recommender Systems as Matrix Completion

Problem

- Every user rates few items (1 %)
- How to infer missing ratings?

Example



Satoshi	?	5	2	?
Kasumi	4	1	?	5
Takeshi	3	3	1	4
Joy	5	?	2	?

Recommender Systems as Matrix Completion

Problem

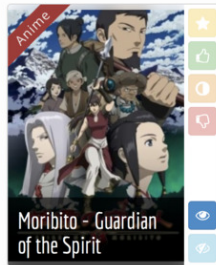
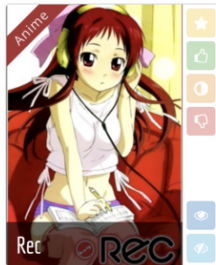
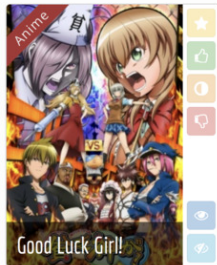
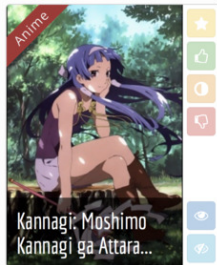
- Every user rates few items (1 %)
- How to infer missing ratings?

Example



Satoshi	3	5	2	2
Kasumi	4	1	4	5
Takeshi	3	3	1	4
Joy	5	2	2	5

Preference Elicitation: select an informative batch of K items



Preference Elicitation: learn user embeddings in latent space



Matrix factorization for collaborative filtering

Approximate R ratings $n \times m$ by learning embeddings for user and item

$$\left. \begin{array}{l} U \text{ user embeddings } n \times d \\ V \text{ item embeddings } m \times d \end{array} \right\} \text{ such that } R \simeq UV^T$$

Fit

Learn U and V to minimize $\|R - UV^T\|_2^2 + \lambda \cdot \text{regularization}$

Predict: Will user i like item j ?

Just compute $\langle \mathbf{u}_i, \mathbf{v}_j \rangle$

The actual model also contains bias terms for user i and item j

$$r_{ij} = \mu + w_i^u + w_j^v + \langle \mathbf{u}_i, \mathbf{v}_j \rangle$$

How to model side information?

If you know user i watched item j at the **cinema** (or on TV, or on smartphone), how to model it?

r_{ij} : rating of user i on item j

Collaborative filtering

$$r_{ij} = w_{\text{user } i} + w_{\text{item } j} + \langle \mathbf{v}_{\text{user } i}, \mathbf{v}_{\text{item } j} \rangle$$

How to model side information?

If you know user i watched item j at the **cinema** (or on TV, or on smartphone), how to model it?

r_{ij} : rating of user i on item j

Collaborative filtering

$$r_{ij} = w_{\text{user } i} + w_{\text{item } j} + \langle \mathbf{v}_{\text{user } i}, \mathbf{v}_{\text{item } j} \rangle$$

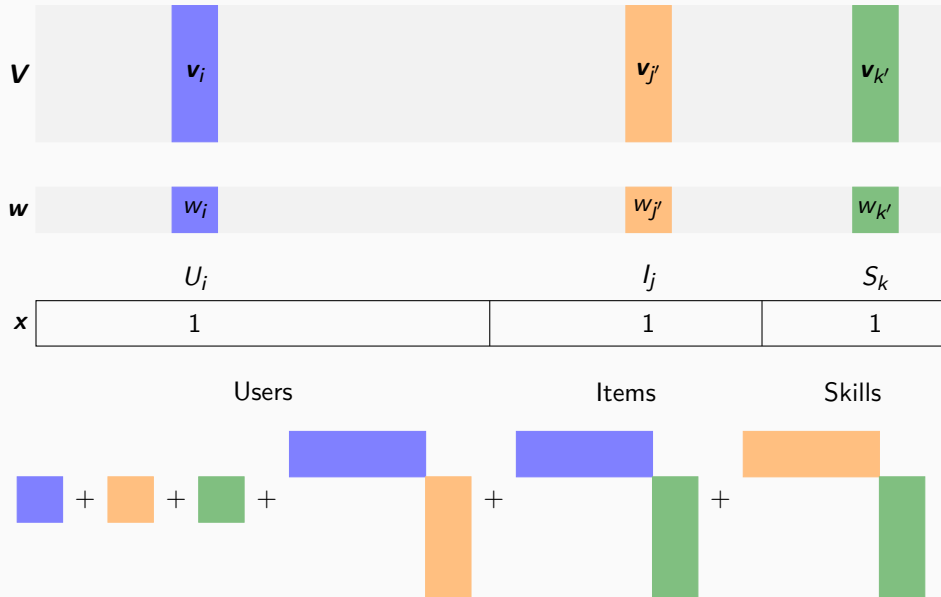
With side information

$$r_{ij} = w_{\text{user } i} + w_{\text{item } j} + w_{\text{cinema}} + \langle \mathbf{v}_{\text{user } i}, \mathbf{v}_{\text{item } j} \rangle + \langle \mathbf{v}_{\text{user } i}, \mathbf{v}_{\text{cinema}} \rangle + \langle \mathbf{v}_{\text{item } j}, \mathbf{v}_{\text{cinema}} \rangle$$

Encoding the problem using sparse features

Users			Items				Formats		
U_1	U_2	U_3	I_1	I_2	I_3	I_4	cinema	TV	mobile
0	1	0	0	1	0	0	0	1	0
0	0	1	0	0	1	0	0	1	0
0	1	0	0	0	1	0	1	0	0
0	1	0	0	1	0	0	1	0	0
1	0	0	0	0	0	1	0	1	0

Graphically: factorization machines



Formally: factorization machines

Learn bias w_k and embedding \mathbf{v}_k for each feature k such that:

$$y(\mathbf{x}) = \mu + \underbrace{\sum_{k=1}^K w_k x_k}_{\text{linear regression}} + \underbrace{\sum_{1 \leq k < l \leq K} x_k x_l \langle \mathbf{v}_k, \mathbf{v}_l \rangle}_{\text{pairwise interactions}}$$

This model is for regression

If classification, use a link function like softmax/sigmoid or Gaussian CDF

Steffen Rendle. “Factorization Machines with libFM”. In: *ACM Transactions on Intelligent Systems and Technology (TIST)* 3.3 (2012), 57:1–57:22. DOI: 10.1145/2168752.2168771

Training using, for example, SGD

Take a batch (\mathbf{X}_B, y_B) and update the parameters such that the error is minimized.

- Loss in classification: cross-entropy
- Loss in regression: squared error

Algorithm 1 SGD

```
for batch  $\mathbf{X}_B, y_B$  do  
    for  $k$  feature involved in this batch  $\mathbf{X}_B$  do  
        Update  $w_k, \mathbf{v}_k$  to decrease loss estimate  $\mathcal{L}$  on  $\mathbf{X}_B$   
    end for  
end for
```

Why do we prefer distributions over point estimates?

- Because we can measure **uncertainty**
- More robust for critical applications
- Can guide sequential estimation (preference elicitation)

Variational inference

Approximate true posterior with an easier distribution (Gaussian)

Idea: increase the ELBO \Rightarrow increase the objective

$$\begin{aligned}\log p(\mathbf{y}) &\geq \sum_{i=1}^N \underbrace{\mathbb{E}_{q(\theta)}[\log p(y_i|x_i, \theta)] - \text{KL}(q(\theta)||p(\theta))}_{\text{Evidence Lower Bound (ELBO)}} \\ &= \sum_{i=1}^N \mathbb{E}_{q(\theta)}[\log p(y_i|x_i, \theta)] - \text{KL}(q(w_0)||p(w_0)) - \sum_{k=1}^K \text{KL}(q(\theta_k)||p(\theta_k))\end{aligned}$$

Needs to be rescaled for mini-batching (see in the paper)

Variational inference

$$\text{Priors } p(w_k) = \mathcal{N}(\nu_{g(k)}^w, 1/\lambda_{g(k)}^w) \quad p(v_{kf}) = \mathcal{N}(\nu_{g(k)}^{v,f}, 1/\lambda_{g(k)}^{v,f})$$

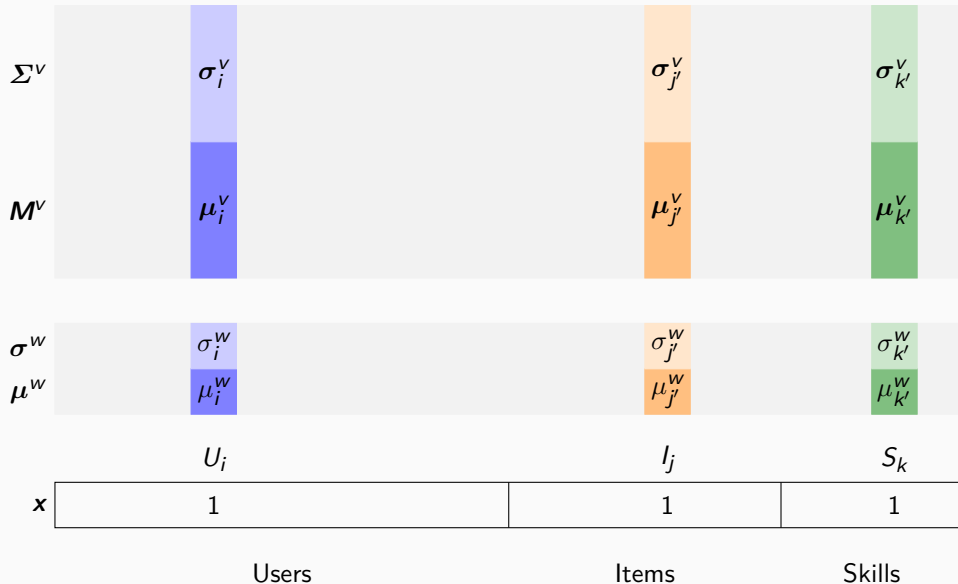
$$\text{Approx. posteriors } q(w_k) = \mathcal{N}(\mu_k^w, (\sigma_k^w)^2) \quad q(v_{kf}) = \mathcal{N}(\mu_k^{v,f}, (\sigma_k^{v,f})^2)$$

Idea: increase the ELBO \Rightarrow increase the objective

$$\begin{aligned} \log p(\mathbf{y}) &\geq \sum_{i=1}^N \underbrace{\mathbb{E}_{q(\theta)}[\log p(y_i|x_i, \theta)] - \text{KL}(q(\theta)||p(\theta))}_{\text{Evidence Lower Bound (ELBO)}} \\ &= \sum_{i=1}^N \mathbb{E}_{q(\theta)}[\log p(y_i|x_i, \theta)] - \text{KL}(q(w_0)||p(w_0)) - \sum_{k=1}^K \text{KL}(q(\theta_k)||p(\theta_k)) \end{aligned}$$

Needs to be rescaled for mini-batching (see in the paper)

Graphically: Variational Factorization Machines



Algorithm 2 Variational Training (SGVB) of FMs

for each batch $B \subseteq \{1, \dots, N\}$ **do**

 Sample $w_0 \sim q(w_0)$

for $k \in F(B)$ feature involved in batch B **do**

 Sample S times $w_k \sim q(w_k)$, $\mathbf{v}_k \sim q(\mathbf{v}_k)$

end for

for $k \in F(B)$ feature involved in batch B **do**

 Update parameters $\mu_k^w, \sigma_k^w, \mu_k^v, \sigma_k^v$ to increase ELBO estimate

end for

 Update hyper-parameters $\mu_0, \sigma_0, \nu, \lambda, \alpha$

 Keep a moving average of the parameters to compute mean predictions

end for

Then σ can be reused for preference elicitation (see how in the paper)

Stochastic weight averaging

A beneficial regularization: keep all weights over training epochs and average them.
Connections to Polyak-Ruppert averaging, aka stochastic weight averaging

Experiments on real data

Task	Dataset	#users	#items	#entries	Sparsity
Regression	movie100k	944	1683	100000	0.937
	movie1M	6041	3707	1000209	0.955
Classification	movie100	100	100	10000	0
	movie100k	944	1683	100000	0.937
	movie1M	6041	3707	1000209	0.955
	Duolingo	1213	2416	1199732	0.828

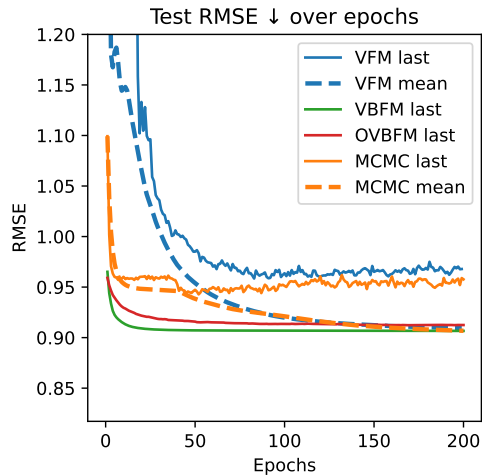
Models

- The proposed approach VFM
- libFM MCMC implementation
- We found another preprint VBFM [2] only for regression

Results on regression

RMSE	Movie100k	Movie1M
MCMC	0.906	0.840
VFM	0.906	0.854
VBFM	0.907	0.856
OVBFM	0.912	0.846

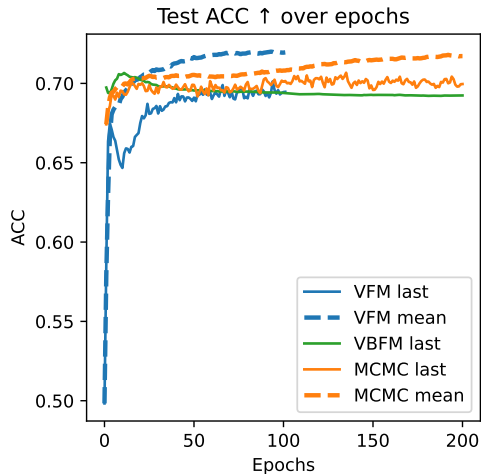
OVBFM is online (batch size = 1) of VBFM



Results on classification

ACC	Movie100k	Movie1M	Duolingo
MCMC	0.717	0.739	0.848
VFM	0.722	0.746	0.846
VBFM	0.692	0.732	0.842

In the paper, we also report AUC and mean average precision.



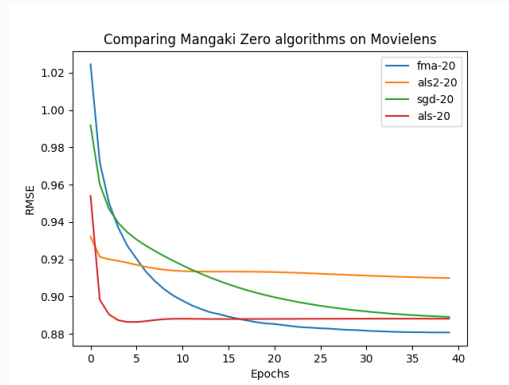
- FMs are a strong baseline
- In this paper we present a variational approach for learning them
 - so that we can deal with u n c e r t a i n t y
- Our method is batched so suitable for large-scale datasets
- We have better performance on some (not all) classification datasets; perhaps due to Adam optimizer or stochastic weight averaging (beneficial regularization)

Thanks for listening!

VFM is implemented in TF & PyTorch

$\mathbb{E}_{q(\theta)}[\log p(y_i|\mathbf{x}_i, \theta)]$ becomes
`outputs.log_prob(observed).mean()`
Same implementation for classification
and regression: the only difference in the
distribution (Bernoulli vs. Gaussian)

Feel free to try it on GitHub (`vfm.py`):
github.com/jilljenn/vae



See more benchmarks on
github.com/mangaki/zero

- [1] Steffen Rendle. “Factorization Machines with libFM”. In: *ACM Transactions on Intelligent Systems and Technology (TIST)* 3.3 (2012), 57:1–57:22. DOI: 10.1145/2168752.2168771.
- [2] Avijit Saha et al. “Scalable Variational Bayesian Factorization Machine”. 2017.